## UNIVERSITY OF TWENTE

Department of Electrical Engineering, Mathematics and Computer Science

## Solution exam Linear Algebra on Tuesday July 21, 2020, 18.15 – 20.15 hours.

2.

Consider the following system of equations:

$$\begin{cases} x_1 + x_2 + 2x_3 + x_4 = 2\\ \beta x_2 + x_3 + x_4 = 0\\ \alpha x_3 = 0 \end{cases}$$

We known that the solution set of the system is given by:

$$\begin{pmatrix} 2\\1\\0\\-1 \end{pmatrix} + \operatorname{Span} \left\{ \begin{pmatrix} 0\\1\\0\\-1 \end{pmatrix} \right\}$$

Determine all possible  $\alpha$  and  $\beta$  for which the above is correct.

First we check whether the given solution satisfies our linear system of equations. First we check whether

$$\begin{pmatrix} 2\\1\\0\\-1 \end{pmatrix}$$

satisfies the given system of equations. It is easily seen that this yields that  $\beta = 1$ . Next we check whether

$$\begin{pmatrix} 0\\1\\0\\-1 \end{pmatrix}$$

satisfies the homogeneous version of our system of equations:

$$\begin{cases} x_1 + x_2 + 2x_3 + x_4 = 0\\ \beta x_2 + x_3 + x_4 = 0\\ \alpha x_3 = 0 \end{cases}$$

and it easily see that this is the case for  $\beta = 1$ . We still have not found any restriction on  $\alpha$ . However, we have not checked whether there are additional solutions. The augmented matrix of the system:

$$\begin{pmatrix} 1 & 1 & 2 & 1 & 2 \\ 0 & \beta & 1 & 1 & 0 \\ 0 & 0 & \alpha & 0 & 0 \end{pmatrix}$$

is already in the echelon form (given  $\beta = 1$ ). However if  $\alpha = 0$  then we have only two pivots and two free variables and hence we will find additional solutions. Therefore, we will find our solution set (with one free variable) only if  $\alpha \neq 0$ .

For which values of  $\alpha$  is the matrix:

 $\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \\ 0 & \alpha & 1 \end{pmatrix}$ 

diagonalizable.

Let us compute the eigenvalues of this matrix. The characteristic polynomial is

$$p(\lambda) = \det \begin{pmatrix} \lambda - 1 & 0 & -1 \\ 0 & \lambda - 1 & -\alpha \\ 0 & -\alpha & \lambda - 1 \end{pmatrix} = (\lambda - 1) \left[ (\lambda - 1)^2 - \alpha^2 \right]$$

The eigenvalues are the zeros of this polynomial and hence equal to 1,  $1 - \alpha$  and  $1 + \alpha$ . Clearly the eigenvalues are all distinct for  $\alpha \neq 0$ . If all eigenvalues are distinct then it is known that the matrix is diagonalizable.

For  $\alpha = 0$  we find:

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

and we find that we have a triple zero of the characteristic polynomial in 0. Therefore, the matrix is diagonalizable if we can find three independent eigenvectors. However, if we solve

$$(I - A)\mathbf{x} = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \mathbf{x} = \mathbf{0}$$

then we find:

$$\mathbf{x} \in \operatorname{Span} \left\{ \begin{pmatrix} 1\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0 \end{pmatrix} \right\}$$

and hence we can only find two independent eigenvectors. Therefore for  $\alpha = 0$  the matrix is not diagonalizable.

4.

Given are matrices A and B and C  

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix}$$
Find all matrices X such that  $AX - XB = C$ .  
Let

$$X = \begin{pmatrix} x_1 & x_3 \\ x_2 & x_4 \end{pmatrix}$$

3.

Working out AX - XB = C we then find:

$$-x_1 + x_2 - x_3 = -1$$
$$x_4 = 1$$

We find the following solution set:

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \operatorname{Span} \left\{ \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \right\}$$

5.

Find all possible  $\alpha$  for which the volume of the parallelepiped with vertices (0, 0, 0), (0, 1, 0),  $(\alpha, 0, \alpha)$  and  $(2, 0, \alpha)$  is equal to 3.

The volume of the parallelepiped is given by:

$$\left| \det \begin{pmatrix} 0 & \alpha & 2 \\ 1 & 0 & 0 \\ 0 & \alpha & \alpha \end{pmatrix} \right| = \left| -\alpha^2 + 2\alpha \right|$$

We need either:

$$-\alpha^2 + 2\alpha = 3$$

or

$$-\alpha^2 + 2\alpha = -3$$

The first one does not yield any solutions. The second one yields  $\alpha = -3$  or  $\alpha = 1$ .

6.

Consider an invertible matrix  $A \in \mathbb{R}^{n \times n}$ .

a) If  $\lambda$  is an eigenvalue of A show that  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .

If  $\lambda$  is an eigenvalue of A then clearly  $\lambda \neq 0$  (matrix is invertible). Moreover there exists  $\mathbf{x} \neq \mathbf{0}$  such that

 $A\mathbf{x} = \lambda \mathbf{x}$ 

multiplying the equation with  $\lambda^{-1}A^{-1}$  on the left we obtain:

$$\lambda^{-1}\mathbf{x} = A^{-1}\mathbf{x}$$

but this means that  $\lambda^{-1}$  is an eigenvalue of  $A^{-1}$ .

b) Given is that the matrix  $B = A^3 - 2A^2$  is invertible. Show that A does **not** have eigenvalue 2

Assume 2 is an eigenvalue of A. Then there exists  $\mathbf{x} \neq \mathbf{0}$  such that

 $A\mathbf{x} = 2\mathbf{x}$ 

but then:

 $B\mathbf{x} = (A^3 - 2A^2)\mathbf{x} = (8 - 8)\mathbf{x} = \mathbf{0}$ 

But since  $\mathbf{x} \neq \mathbf{0}$  this yields a contradiction with *B* invertible. Hence *A* does **not** have eigenvalue 2

7.

We have the following matrix:

$$A = \begin{pmatrix} \alpha & \alpha + \beta - 1 & -1 \\ 2 - \alpha & 1 - \beta - \alpha & -1 \\ \alpha & \alpha - 2 & -1 \end{pmatrix}$$

We know that a basis for  $\operatorname{Null} A$  is given by:

$$\left\{ \begin{pmatrix} 1\\0\\1 \end{pmatrix} \right\}$$

while a basis for  $\operatorname{Col} A$  is given by:

$$\left\{ \begin{pmatrix} 1\\0\\1 \end{pmatrix}, \begin{pmatrix} 0\\1\\0 \end{pmatrix} \right\}$$

Determine 
$$\alpha$$
 and  $\beta$ .

Given our basis for Null A, we know that we must have:

$$A\begin{pmatrix}1\\0\\1\end{pmatrix} = \mathbf{0}$$

This yields  $\alpha = 1$  and hence:

$$A = \begin{pmatrix} 1 & \beta & -1 \\ 1 & -\beta & -1 \\ 1 & -1 & -1 \end{pmatrix}$$

It is easily verified that the first and third column of A are in the given Col A. However, the second column of A is only in the given Col A if  $\beta = -1$ . We find:

It is easily verified that this matrix has the required  $\operatorname{Col} A$  and  $\operatorname{Null} A$ .

8.

 $T: \mathbb{R}^2 \to \mathbb{R}^2$  is the linear transformation which first mirrors each point  $(x_1, x_2) \in \mathbb{R}^2$ in the line y = x and next rotates around the origin over  $\alpha$  radians (counterclockwise). The representation matrix of T is given by:

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Determine  $\alpha \in [0, 2\pi)$ .

Let's first consider (1,0). After the mirroring this is in (0,1). The vector (0,1) should then be rotated  $\alpha$  radians counterclockwise and (according to the representation matrix) end up in (1,0). It is easily seen that this is a rotation over  $3\pi/2$  radians.

Let's also consider (0, 1). After the mirroring this is in (1, 0). The vector (1, 0) should then be rotated  $\alpha$  radians counterclockwise and (according to the representation matrix) end up in (0, -1). It is easily seen that this is also a rotation over  $3\pi/2$  radians. Therefore  $\alpha = 3\pi/2$ .

9.

Is the set $S =$	$\{(x, y, z) \in \mathbb{R}^3$	(x-z)(y-z)  = 0	} a subspace of $\mathbb{R}^3$ ?
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For a subspace we have two requirements: If  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are in the set S then we should have:

 $\lambda \mathbf{x}_1 \in S$ 

for all  $\lambda$  and

$$\mathbf{x}_1 + \mathbf{x}_2 \in S.$$

The first property is satisfied in this case. However, the second property is not satisfied. For instance:

$$\begin{pmatrix} 1\\0\\1 \end{pmatrix}, \quad \begin{pmatrix} 0\\1\\1 \end{pmatrix}$$

are both in S but their sum:

$$\begin{pmatrix} 1\\0\\1 \end{pmatrix} + \begin{pmatrix} 0\\1\\1 \end{pmatrix} = \begin{pmatrix} 1\\1\\2 \end{pmatrix}$$

is clearly not is S. Therefore it is not a subspace.